Def (1) The <u>nxn</u> identity matrix is the matrix  $I_n$  whose columns are the standard basis vectors  $\overrightarrow{e_1}$ ,  $\overrightarrow{e_2}$ , ...,  $\overrightarrow{e_n}$ .

e.g. 
$$I_2 = \begin{bmatrix} I & O \\ O & I \end{bmatrix}$$
,  $I_3 = \begin{bmatrix} I & O & O \\ O & I & O \\ O & O & I \end{bmatrix}$ 

- (2) The <u>inverse</u> of an  $n \times n$  matrix A is the matrix  $A^{-1}$  with  $AA^{-1} = A^{-1}A = I_n$ .
- Note (1) The inverse of an nxn matrix is an nxn matrix.
  - (2) The inverse of a nonsquare matrix is undefined.
  - (3) We have  $I_nA = AI_n = A$  for any  $n \times n$  matrix A. (cf.  $1 \cdot a = a \cdot 1 = a$  for any  $a \in \mathbb{R}$ )
  - (4) We often write I in place of  $I_n$ .
- $\underline{\text{Def}} \quad \text{(I)} \quad \text{The } \underline{\text{identity transformation}} \quad \text{on } \mathbb{R}^n \text{ is the linear transformation}$   $\mathbb{1}_n : \mathbb{R}^n \longrightarrow \mathbb{R}^n \text{ with } \mathbb{1}_n(\overrightarrow{x}) = \overrightarrow{x}.$ 
  - (2) The <u>inverse</u> of a linear transformation  $T: \mathbb{R}^n \longrightarrow \mathbb{R}^n$  is the linear transformation  $T^{-1}: \mathbb{R}^n \longrightarrow \mathbb{R}^n$  with  $T \circ T^{-1} = T^{-1} \circ T = \mathbf{1}_n$ .
- Note (1) The standard matrix of 1n is In.
  - (2) A linear transformation T has an inverse.

Prop If a linear transformation  $T: \mathbb{R}^n \longrightarrow \mathbb{R}^n$  with standard matrix A has an inverse  $T^{-1}$ , the standard matrix of  $T^{-1}$  is  $A^{-1}$ .  $T \circ T^{-1} = T^{-1} \circ T = \mathbf{1}_n \iff AA^{-1} = A^{-1}A = \mathbf{1}_n.$ 

Thm A square matrix A has an inverse  $\iff$  RREF(A)=I

<u>pf</u> Take the linear transformation T with standard matrix A A has an inverse

 $\iff$  RREF(A) has a leading 1 in every row and column

 $\iff$  RREF(A)=I

 $\frac{\text{Prop}}{\text{Let}} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  be an arbitrary 2×2 matrix.

(1) If we have ad-bc=0, then  $A^{-1}$  does not exist.

(2) Otherwise, we have  $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d-b\\-c a \end{bmatrix}$ 

 $\underline{Prop}$  Let A be a square matrix with an inverse  $A^{-1}$ . If B is the matrix formed by concatenating A and I, then RREF(B) is formed by concatenating I and  $A^{-1}$ .

$$B = [A \mid I] \Rightarrow RREF(B) = [I \mid A^{-1}]$$

Ex For each linear transformation, find the standard matrix of its inverse if it exists.

(1)  $T_1: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  which maps  $\overrightarrow{e_1}$  to  $\overrightarrow{e_1} - 3\overrightarrow{e_2}$  and  $\overrightarrow{e_2}$  to  $\overrightarrow{e_2}$ .

$$\underline{S_0 \setminus} \quad T_1(\overrightarrow{e_1}) = \overrightarrow{e_1} - 3\overrightarrow{e_2} = \begin{bmatrix} 1 \\ -3 \end{bmatrix} \quad \text{and} \quad T_1(\overrightarrow{e_2}) = \overrightarrow{e_2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

 $\Rightarrow$  The standard matrix of Ti is

$$A' = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}$$

which has an inverse  $(1 \cdot 1 - (-3) \cdot D = 1 \neq D)$ 

 $\Rightarrow$  T, has an inverse with standard matrix

$$A_{i}^{-1} = \frac{1}{1 \cdot 1 - (-3) \cdot D} \begin{bmatrix} 1 & D \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & D \\ 3 & 1 \end{bmatrix}$$

(2)  $T_2: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  with

$$T_{2}(\overrightarrow{X}) = \begin{bmatrix} X_{1} - X_{2} \\ -X_{1} + X_{2} \end{bmatrix} \quad \text{for } \overrightarrow{X} = \begin{bmatrix} X_{1} \\ X_{2} \end{bmatrix}$$

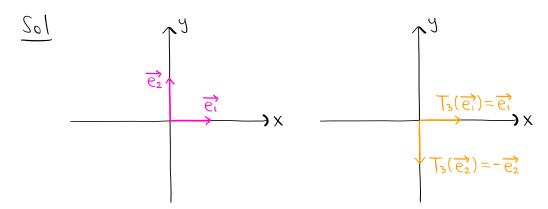
Sol The standard matrix of T2 is

$$A_2 = \begin{bmatrix} I & -I \\ -I & I \end{bmatrix}$$

which does not have an inverse  $(1 \cdot 1 - (-1) \cdot (-1) = D)$ 

 $\Rightarrow$  T<sub>2</sub> does not have an inverse

(3)  $T_3: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  which reflects each vector through the x-axis.



$$T_3(\overrightarrow{e_1}) = \overrightarrow{e_1} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
 and  $T_3(\overrightarrow{e_2}) = -\overrightarrow{e_2} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$ 

 $\Rightarrow$  The standard matrix of T<sub>3</sub> is

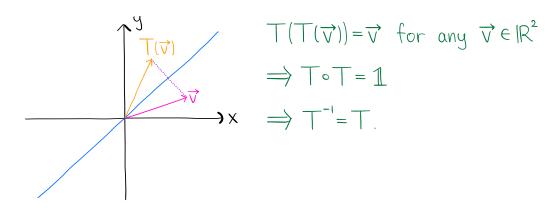
$$A^3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

which has an inverse  $(1\cdot(-1)-D\cdot D=-1\neq D)$ 

 $\Rightarrow$  T3 has an inverse with standard matrix

$$A_{3}^{-1} = \frac{1}{1 \cdot (-1) - O \cdot O} \begin{bmatrix} -1 & O \\ O & I \end{bmatrix} = \begin{bmatrix} 1 & O \\ O & -I \end{bmatrix} (= A_{3})$$

Note In fact, if  $T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  is a reflection through a line, it is invertible with  $T^{-1} = T$ .



- (4)  $T_4: IR^2 \longrightarrow IR^2$  which rotates each vector about the origin through  $\frac{\pi}{4}$  radians
  - Sol The standard matrix of T4 is

$$A_4 = \begin{bmatrix} \cos(\pi/4) & -\sin(\pi/4) \\ \sin(\pi/4) & \cos(\pi/4) \end{bmatrix} = \begin{bmatrix} 1/\sqrt{12} & -1/\sqrt{12} \\ 1/\sqrt{12} & 1/\sqrt{12} \end{bmatrix}$$

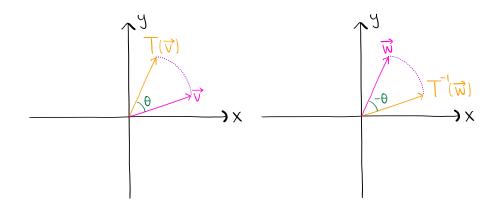
which has an inverse  $(\sqrt{2}\cdot\sqrt{2}-(-\sqrt{2})\cdot\sqrt{2}=1\pm0)$ 

 $\Rightarrow$  T4 has an inverse with standard matrix

$$A_{4}^{-1} = \frac{1}{\sqrt{\sqrt{2} \cdot \sqrt{\sqrt{2}} - (-\sqrt{\sqrt{2}}) \cdot \sqrt{\sqrt{2}}}} \begin{bmatrix} \sqrt{\sqrt{2}} & \sqrt{\sqrt{2}} \\ -\sqrt{\sqrt{2}} & \sqrt{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \sqrt{\sqrt{2}} & \sqrt{\sqrt{2}} \\ -\sqrt{\sqrt{2}} & \sqrt{\sqrt{2}} \end{bmatrix}$$

Note In fact, if  $T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$  is a rotation about the origin through  $\theta$  radians, it is invertible with  $T^{-1}$  being the rotation about the origin through  $-\theta$  radians.

O rads clockwise



 $T \circ T^{-1} = T^{-1} \circ T = 1$  (rotation through  $\theta - \theta = 0$  radians)

(5)  $T_5: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$  with standard matrix

$$A_{5} = \begin{bmatrix} 2 & 0 & 3 \\ 1 & 2 & 2 \\ 0 & 3 & 1 \end{bmatrix}$$

Sol Take the matrix formed by concatenating A5 and I.

$$\begin{bmatrix} 2 & 0 & 3 & | & 1 & 0 & 0 \\ | & 2 & 2 & | & 0 & | & 0 \\ | & 0 & 3 & | & 0 & 0 & | \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} | & 0 & 0 & | & -4 & 9 & -6 \\ | & 0 & | & 0 & | & -1 & 2 & -1 \\ | & 0 & 0 & | & 3 & -6 & 4 \end{bmatrix}$$

$$A_{5} \qquad I \qquad RREF(A_{5}) = I \qquad A_{5}^{-1}$$

 $A_5$  has an inverse  $(RREF(A_5) = I)$ 

 $\Rightarrow$  T5 has an inverse with standard matrix

$$A_{5}^{-1} = \begin{bmatrix} -4 & 9 & -6 \\ -1 & 2 & -1 \\ 3 & -6 & 4 \end{bmatrix}$$

(6)  $T_6: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$  with standard matrix

$$A_6 = \begin{bmatrix} 1 & 0 & -1 \\ 3 & 2 & -3 \\ 1 & 1 & -1 \end{bmatrix}$$

Sol Take the matrix formed by concatenating Ao and I.

$$\begin{bmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 3 & 2 & -3 & 0 & 1 & 0 \\ 1 & 1 & -1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & -1 & 0 & 1 & -2 \\ 0 & 1 & 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 & -1 & 2 \end{bmatrix}$$

$$A_6 \qquad I \qquad RREF(A_6)$$

 $A_6$  does not have an inverse (RREF( $A_6$ )  $\neq I$ )

$$\Rightarrow$$
 T<sub>6</sub> does not have an inverse